

top to drag a ball into the machine. Pistons and bungee cords lift the assembly back up, and another piston punches the ball out using compressed air, shooting it toward the goal.

The Mechanical Bulls from Smithtown, on New York's Long Island, wanted their robot to be primarily an offensive shooter, so they built in a catapult molded to fit the game ball. A single-motor winch brings the scoop back and launches the ball up to 19 feet. Brian Sheridan, 17, said that the team molded the catapult arm out of two PVC pipes, making it durable and flexible. In fact, the Mechanical Bulls are working on a patent for their model.



The John Dewey High School team from Brooklyn, N.Y., wanted to mix things up with their robot. "Our team decided to do something new," Ihar Husar, 16, said. Front claws wrap the ball and flip it up onto a catapult, which uses a lightweight pneumatic system for rapid launching. The team ran into some trouble when balls kept rolling off the back of the catapult, so they installed the poles on either side for more secure handling. The team's bot made all its shots during the autonomous periods, and Mei Vi, 16, credited Husar for his programming of the robot.

The team from Miller Place, N.Y., went for versatility with their robot. During the six weeks the teams had to build, Miller Place designed two prototypes; the one they brought to FIRST could reverse, pass the ball, and shoot. A ramp dropped, and gears at the top of it turned to bring in the ball. Once the ramp lifted and the ball was secured in the catapult, pneumatics and a spring-loaded assist would flip the hoop up, launching the ball. FIRST is a demanding competition, though: When PM stopped by their booth, the Miller Place team was scrambling to make repairs, as some of the wells had broken in a previous match, and fluid had gotten into the electronics.

Students from Plainview–Old Bethpage Central School District on Long Island took a different approach to the game. The robot sported a mallet, which team member Michael Saltzman, 17, said they nicknamed Thor's Hammer. The mallet can swing backward almost 270 degrees before swinging back down to kick the ball. And it's adjustable: The team can add or drop weight for more or less range on their shots. They installed two motors on each side, ensuring that their robot had a steady platform and wouldn't get pushed around by the other competitors.

The coolest part of the Tomahawk robot by Townsend Harris High School students from Queens, N.Y., is the ultrasonic sensors. With these the bot can sense a ball in front of it and deploy two side hoops to pick it up. The sensors also flashed a red light on the back when the robot was within range so the operators would know when to take a shot. The robot's range was only 8 to 10 feet, but Vinay Khemlani, 17, and Vijay Sookai, 16, said the team had learned to take running shots to maximize the distance.

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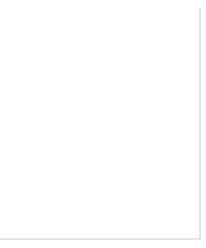
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